

Tutorial 4 – From Assembly to C + Gates SOLUTIONS

1. (a) From the following fragment of assembly code, complete the table:

1. LDS R16, \$0050
2. LDI R17, \$51
3. STS \$004A, R16
4. STS \$004B, R17

Registers and Mem.	Initial Values	After 1.	After 2.	After 3.	After 4.
(PC)	\$00	\$02	\$03	\$05	\$07
(R16)	\$00	\$42	\$42	\$42	\$42
(R17)	\$FF	\$FF	\$51	\$51	\$51
(\$004A)	\$3C	\$3C	\$3C	\$42	\$42
(\$004B)	\$1D	\$1D	\$1D	\$1D	\$51
(\$0050)	\$42	\$42	\$42	\$42	\$42
(\$0051)	\$B9	\$B9	\$B9	\$B9	\$B9

(b) What is the value in the following registers and/or memory locations after executing the following instructions?

1. LDS R16, \$0400

<i>Before</i>	<i>After</i>
R16 = \$76	R16 = \$89
[\$0400] = \$89	[\$0400] = \$89

2. LDI R16, \$04

<i>Before</i>	<i>After</i>
R16 = \$76	R16 = \$04
[\$0400] = \$89	[\$0400] = \$89

3. CPI R16, \$76

<i>Before</i>	<i>After</i>
R16 = \$76	R16 = \$76
[\$0400] = \$89	[\$0400] = \$89

-- Flags: Overflow, Negative, Zero, Carry = _ _ _ _ --
-- 0010

Note: The CPI instruction performs subtraction but does not store the result anywhere. Instead it sets the flags in the Condition Code Register.

4. LDS R16, \$0400
 STS \$0401, R16

<u>Before</u>	<u>After</u>
R16 = \$76	R16 = \$89
[\$0400] = \$89	[\$0400] = \$89
[\$0401] = \$00	[\$0401] = \$89

5. ADD R16, R17

<u>Before</u>	<u>After</u>
R16 = \$76	R16 = \$88
R17 = \$12	R17 = \$12

6. AND R16, R17

<u>Before</u>	<u>After</u>
R16 = \$76	R16 = 0111 0110 AND 0001 0010 = \$12
R17 = \$12	R17 = \$12

7. OR R16, R17

<u>Before</u>	<u>After</u>
R16 = \$76	R16 = 0111 0110 OR 0001 0010 = \$76
R17 = \$12	R17 = \$12

8. INC R30

<u>Before</u>	<u>After</u>
R30 = \$79	R30 = \$7A

9. DEC R30

<u>Before</u>	<u>After</u>
R30 = \$00	R30 = \$FF

10. CLR R30

<u>Before</u>	<u>After</u>
R30 = \$FF	R30 = \$00

2. Translate the following Assembly program into C

```
; Project: Moving LEDs  
.include "m169def.inc"
```

```
main: LDI R16, 0xFF ; D is output  
      OUT DDRD, R16  
      LDI R16, 1 ; init count  
  
loop: OUT PORTD, R16 ; display LED  
      CALL wait  
      LSL R16 ; shift left  
      BRNE loop  
      LDI R16, 1 ; if 0 -> 1  
      JMP loop  
  
wait: LDI R31, 255 ; init cnt  
waitloop: DEC R31  
          BRNE waitloop  
          RET
```

```
int count;
```

```
void setup()
```

```
{ pinMode(1, OUTPUT);  
  pinMode(2, OUTPUT);  
  pinMode(3, OUTPUT);  
  count = 0b001;  
}
```

```
void wait()
```

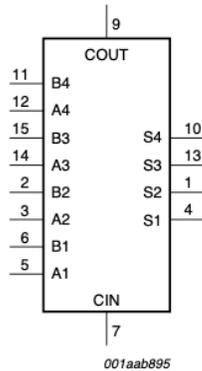
```
{ int i;  
  for (i=255; i>0; i--) ; /* wait */  
}
```

```
void loop()
```

```
{ digitalWrite(1, count & 0b100); // highest bit  
  digitalWrite(2, count & 0b010);  
  digitalWrite(3, count & 0b001); // lowest bit  
  count = count << 1; // shift left  
  if (count > 0b100) count = 0b001;  
  wait();  
}
```

3. Review the Gates required for buildign a hardware Adder

- (a) Half-Adder requires 1 x AND and 1 x XOR.
How can you build this circuit using only NAND and NOR gates?
- (b) How do you connect an LED to a chip output?
Do you need a resistor and if so, which size?
- (c) Review the 74HC283 Adder chip. Which additional pats do you need to build a 2 x 4-bit adder?



No solution given. Ou just need to build this in hardware in the lab.